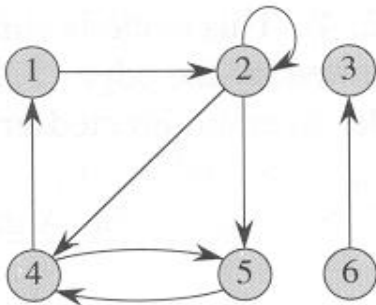


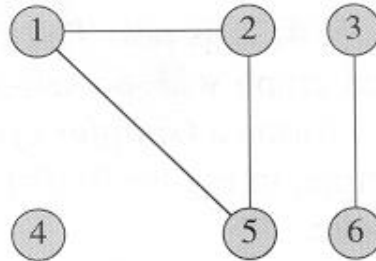
# Elementary Graph Algorithm

# Graph

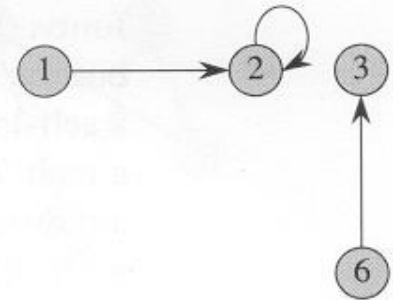
- $G = (V, E)$ 
  - $V$  : set of vertices
  - $E$  : set of edges
    - Directed graph
    - Undirected graph



(a)



(b)



(c)

$V = \{1, 2, 3, 4, 5, 6\}$   
 $E = \{(1, 2), (2, 2), (2, 4), (2, 5), (4, 1), \mathbf{(4, 5)}, \mathbf{(5, 4)}, (6, 3)\}$

$V = \{1, 2, 3, 4, 5, 6\}$   
 $E = \{(1, 2), (1, 5), (2, 4), (3, 6)\}$

Sub-graph of (a)

\* Self-loop

# Graph

- Applications

Graph	Vertices	Edges
통신	전화, 컴퓨터	광섬유 케이블
전기전자 회로	칩, 콘덴서, 저항	선
기계	이음새	스프링, 빔, 막대
급수시스템	저수지, 정화시설	배관
교통	교차로, 공항	고속도로, 항로
일정표	단위작업	선결 조건
소프트웨어 시스템	함수	함수호출
인터넷	웹 페이지	하이퍼 링크
게임	말의 위치	허용된 움직임
분자구조	분자	화학적 연결
사회적 관계	사람	친구관계
경제	주식, 현금	거래

# Graph

- Incident (입사, 투사)

- Edge of digraph:  $(u, v)$

- incident **from**  $u$
- incident **to**  $v$

(ex) edges *incident from* vertex 2:

(ex) edges *incident to* vertex 2:

- Edge of undirected graph:  $(u, v)$

- incident **on**  $u$  and  $v$

(ex) edges *incident on* vertex 2:

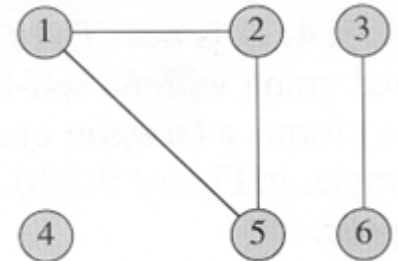
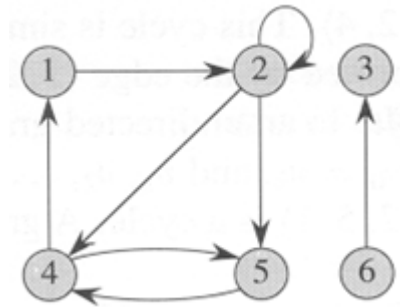
- Adjacent

- Edge of graph:  $(u, v)$

- Vertex  $v$  is *adjacent to* vertex  $u$

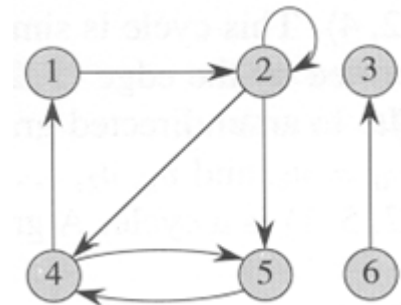
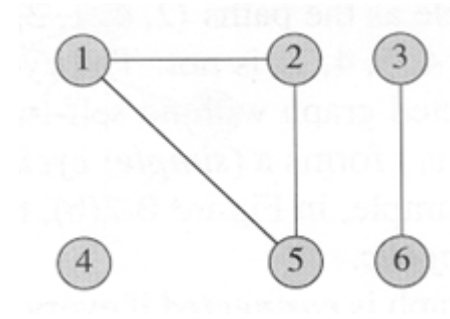
(ex) edge  $(1, 2)$ :

- ❖ Undirected graph: symmetric relation



# Graph

- Degree of a vertex
  - Undirected graph
    - : number of edges *incident on* it
    - (ex)
  - Directed graph
    - Out-degree
      - : number of edges *incident from* it
    - In-degree
      - : number of edges *incident to* it
    - Degree = out-degree + in-degree
    - (ex)



# Graph

- Path

- Sequence of vertices:  $\langle v_0, v_1, \dots, v_k \rangle$ ,  $(v_{i-1}, v_i) \in E$
- Length of a path  
: number of edges in the path

- Cycle

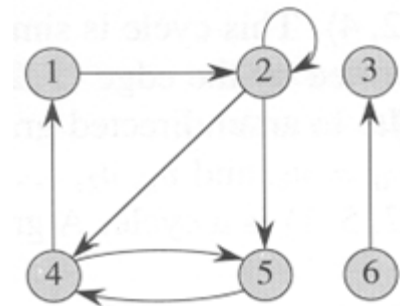
- Path  $\langle v_0, v_1, \dots, v_k \rangle$  if  $v_0 = v_k$

- Reachable

- Vertex  $u'$  is reachable from vertex  $u$   
 $\leftrightarrow$  there is a path from  $u$  to  $u'$   
 $\leftrightarrow u \rightsquigarrow u'$

- Connected

- A graph is connected  
 $\leftrightarrow$  every vertex is reachable from every other vertex



# Representation of Graphs

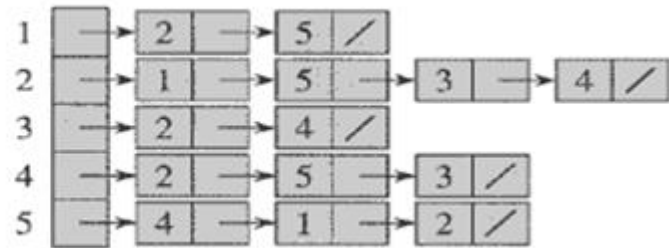
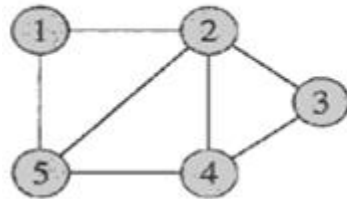
- Adjacency List (인접 리스트)

- Graph 를 Linked list 를 사용하여 표현하는 방법

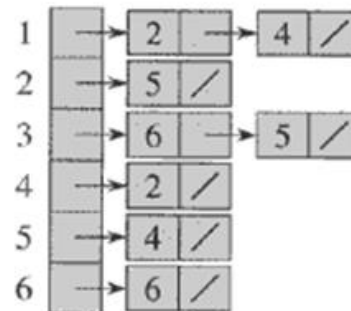
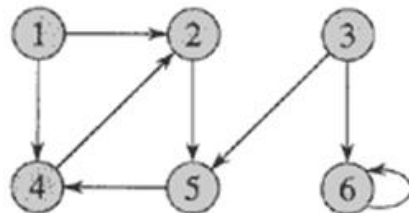
- $Adj[u], u \in V$

For each  $u \in V$ ,  $Adj[u]$  contains all vertices  $v$  such that there is an edge  $(u, v) \in E$

(ex) undirected graph



(ex) digraph



# Representation of Graphs

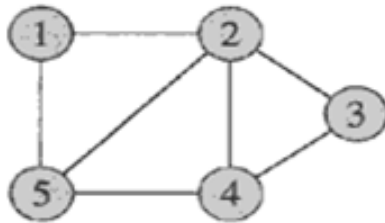
- Adjacency List (인접 리스트)
  - 모든 adjacency list 길이의 합
    - Undirected graph:  $|E|$
    - Directed graph:  $2|E|$
  - Memory requirements
    - $\Theta(|V| + |E|)$
    - Sparse graph ( $|E| \ll |V|^2$ ) 의 표현에 적합
  - Edge  $(u, v)$  존재 여부 확인이 복잡하다
- \* large graph 에 주로 적용



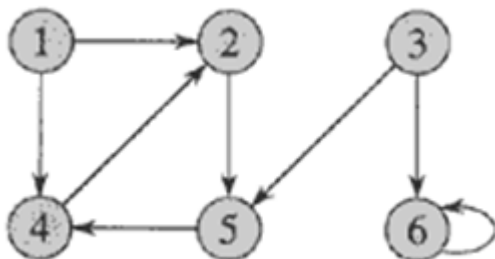
# Representation of Graphs

- Adjacency Matrix (인접 행렬)
  - 2 dim. Array 를 사용하여 그래프 표현
  - $A = (a_{ij})$  ( $i=1, \dots, |V|, j=1, \dots, |V|$ )

$$a_{ij} = \begin{cases} 1 & \text{if } (i, j) \in E \\ 0 & \text{otherwise} \end{cases}$$



	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0



	1	2	3	4	5	6
1	0	1	0	1	0	0
2	0	0	0	0	1	0
3	0	0	0	0	1	1
4	0	1	0	0	0	0
5	0	0	0	1	0	0
6	0	0	0	0	0	1

# Representation of Graphs

- Adjacency Matrix
  - Undirected graph:  $A = A^T$
  - Memory requirements
    - $\Theta(|V|^2)$
    - Dense graph ( $|E| \approx |V|^2$ ) 의 표현에 적합
  - Edge  $(u, v)$  존재 여부 확인이 간단하다
- \* Small graph 에 주로 적용

# Breadth-First Search

- 목적

- 주어진 graph  $G=(V,E)$  와 source vertex  $s$  에 대하여,  $s$  에서 reachable 한 모든 vertex 탐색
- $s$  로 부터 모든 reachable vertex 까지의 distance (smallest number of edges) 계산

- Data

Adj[u]: graph 의 adjacency list

color[u]: 각 vertex 의 status

white - not discovered

gray – discovered but not confirmed

black – discovered and confirmed

$d[u]$ :  $s$  부터  $u$  까지의 distance

$p[u]$ :  $u$  의 predecessor (or parent)

( $u, v$ ) 가 edge 인 경우,  $u$  는  $v$  의 predecessor

$Q$ : queue (first-in first-out)

# Breadth-First Search

- Idea
  - Send a wave out from  $s$ .
    - First hits all vertices 1 edge from  $s$ .
    - From there, hits all vertices 2 edges from  $s$ .
    - Etc.
  - Use FIFO queue  $Q$  to maintain the wavefront
    - $v \in Q$  if and only if wave has hit  $v$  but has not come out of  $v$  yet.

# Breadth-First Search

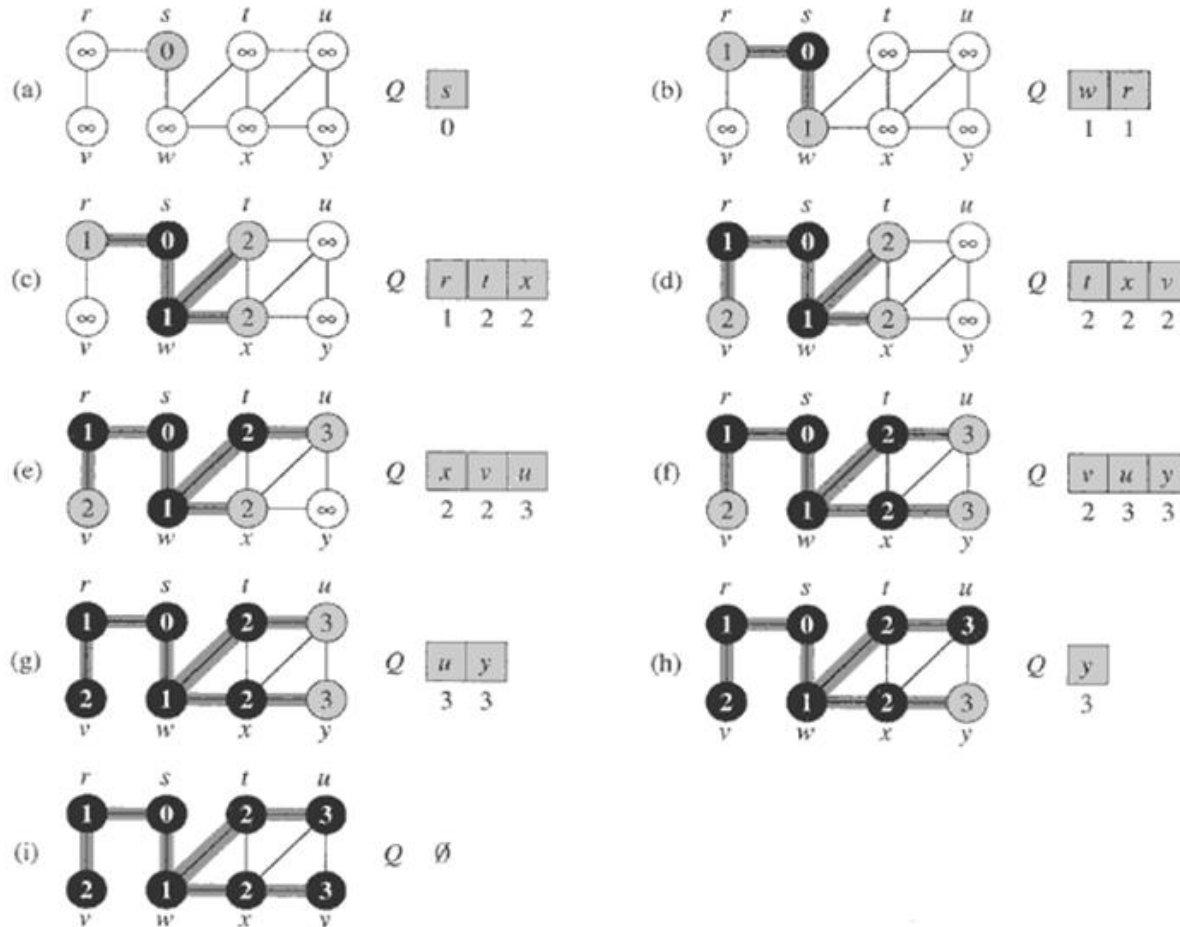
- BFS( $G, s$ )

```
BFS( $G, s$ )
1  for each vertex  $u \in V[G] - \{s\}$ 
2      do  $color[u] \leftarrow WHITE$ 
3           $d[u] \leftarrow \infty$ 
4           $\pi[u] \leftarrow NIL$ 
5   $color[s] \leftarrow GRAY$ 
6   $d[s] \leftarrow 0$ 
7   $\pi[s] \leftarrow NIL$ 
8   $Q \leftarrow \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11     do  $u \leftarrow DEQUEUE(Q)$ 
12         for each  $v \in Adj[u]$ 
13             do if  $color[v] = WHITE$ 
14                 then  $color[v] \leftarrow GRAY$ 
15                      $d[v] \leftarrow d[u] + 1$ 
16                      $\pi[v] \leftarrow u$ 
17                     ENQUEUE( $Q, v$ )
18      $color[u] \leftarrow BLACK$ 
```

- \* running time:  $O(V+E)$ 
  - 초기화: vertex 수에 비례  $O(V)$
  - loop: edge 수에 비례  $O(E)$

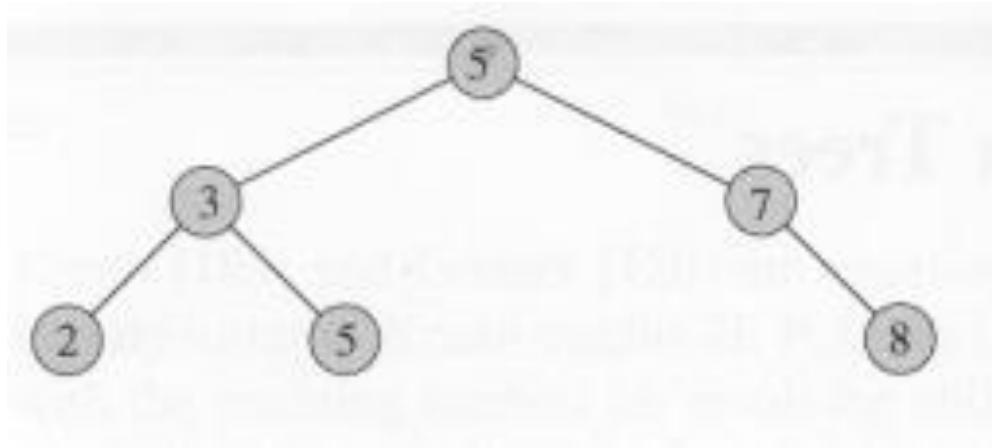
# Breadth-First Search

- Example



# Breadth-First Search

(Q)



# Breadth-First Search

- PRINT-PATH( $G, s, v$ )
  - $s$  부터  $v$  까지의 최단 path (breadth-first path) print
  - $p[v]$  를 trace 하며 인쇄

```
PRINT-PATH( $G, s, v$ )
1  if  $v = s$ 
2    then print  $s$ 
3    else if  $\pi[v] = \text{NIL}$ 
4        then print “no path from”  $s$  “to”  $v$  “exists”
5        else PRINT-PATH( $G, s, \pi[v]$ )
6        print  $v$ 
```



# Depth-First Search

- 목적
  - 주어진 graph  $G=(V,E)$  의 모든 vertex 발견 (discover)
  - 각 vertex 에 대한 time stamps (discovery time, finish time) 기록
- Data
  - Adj[u]: graph 의 adjacency list
  - color[u]: 각 vertex 의 status
    - white - not discovered
    - gray – discovered but not finished
    - black – discovered and finished
  - d[u]: discovery time
  - f[u]: finish time ( $d[u] < f[u]$ )
  - p[u]: u 의 predecessor (or parent)
  - Stack

# Depth-First Search

- Idea
  - Tree 의 pre-order traverse 와 유사
  - discover:  $v_1 \rightarrow v_2 = \text{adj}[v_1] \rightarrow v_3 = \text{adj}[v_2] \rightarrow$
  - finish:  $\dots \rightarrow v_3 \rightarrow v_2 \rightarrow v_1$  방식
- DFS( $G$ )

```
DFS( $G$ )
1  for each vertex  $u \in V[G]$ 
2      do  $color[u] \leftarrow \text{WHITE}$ 
3       $\pi[u] \leftarrow \text{NIL}$ 
4   $time \leftarrow 0$ 
5  for each vertex  $u \in V[G]$ 
6      do if  $color[u] = \text{WHITE}$ 
7          then DFS-VISIT( $u$ )

DFS-VISIT( $u$ )
1   $color[u] \leftarrow \text{GRAY}$       ▷ White vertex  $u$  has just been discovered.
2   $time \leftarrow time + 1$ 
3   $d[u] \leftarrow time$ 
4  for each  $v \in Adj[u]$       ▷ Explore edge  $(u, v)$ .
5      do if  $color[v] = \text{WHITE}$ 
6          then  $\pi[v] \leftarrow u$ 
7              DFS-VISIT( $v$ )
8   $color[u] \leftarrow \text{BLACK}$     ▷ Blacken  $u$ ; it is finished.
9   $f[u] \leftarrow time \leftarrow time + 1$ 
```

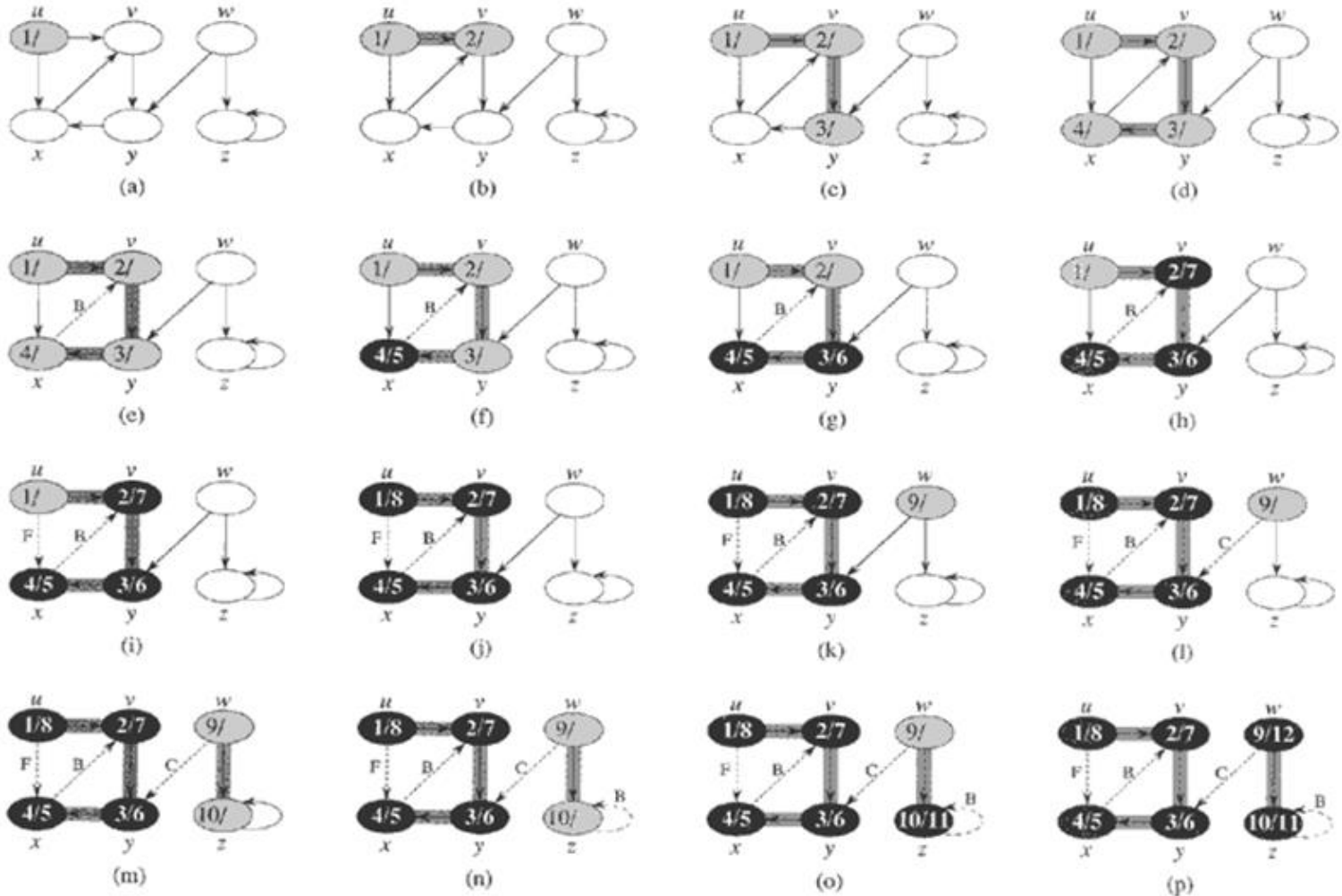
running time:  $\Theta(V+E)$

- 초기화: vertex 수에 비례  $\Theta(V)$

- loop: edge 수에 비례  $\Theta(E)$

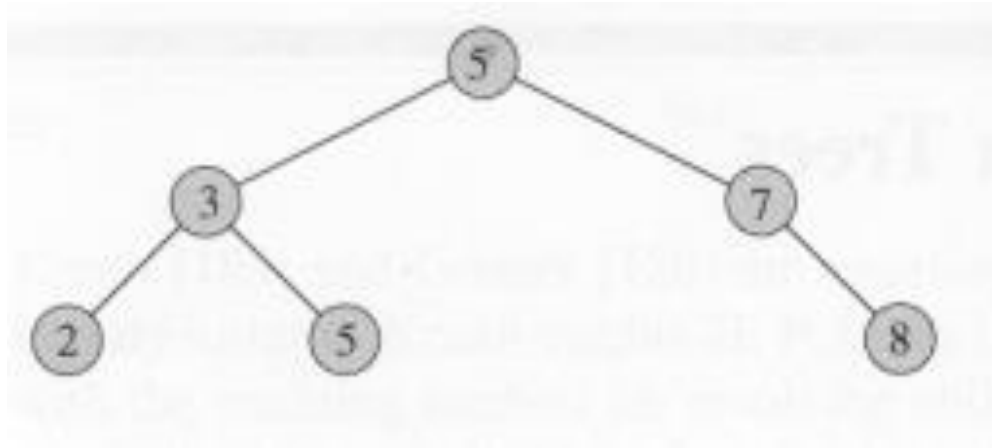
# Depth-First Search

- Example



# Depth-First Search

(Q)

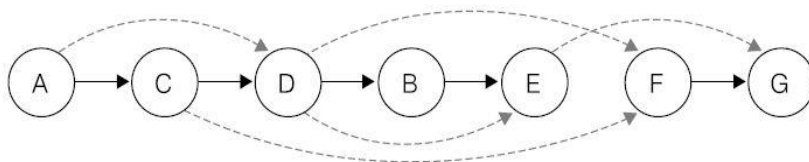
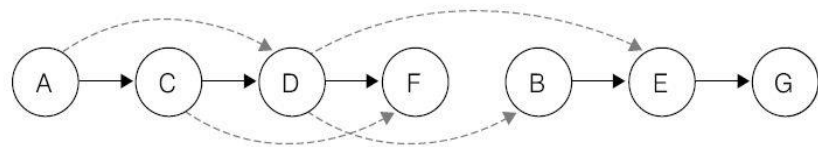
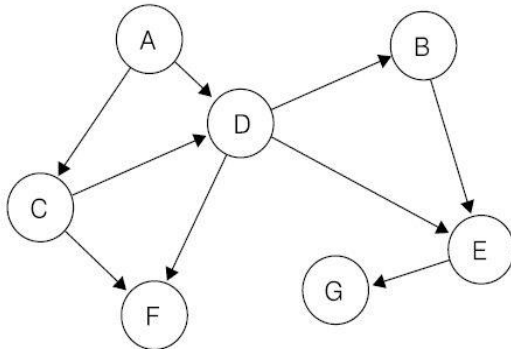


# Topological Sort

- Topological Sort (위상 정렬)
  - directed acyclic graph (dag) 의 모든 vertex 를 linear ordering
  - AOV (activity on vertex) network 에서 먼저 수행해야 될 공정부터 시작해서 일렬로 모든 공정을 나열

Vertex : process

Edge: process 간의 sequence



# Topological Sort

- Algorithm

- 1 DFS( $G$ ) 수행

- 2 vertex 의 linked-list 생성( finish time 역순으로)

- 3 vertex 의 linked-list return

TOPOLOGICAL-SORT( $G$ )

- 1 call DFS( $G$ ) to compute finishing times  $f[v]$  for each vertex  $v$

- 2 as each vertex is finished, insert it onto the front of a linked list

- 3 **return** the linked list of vertices

# Topological Sort

- Example

